

# KINAX 3W2

## Transmitter for Angular Position

### Application

The **KINAX 3W2** (Figs. 1 to 3) converts the angular position of a shaft into a **load independent** direct current signal, proportional to the angular position. The unit is **contact free** and has **minimal mechanical abrasion** on the input shaft. It is a technically purposeful complement to the angle transmitter program. This compacter version is made possible by incorporating newly developed, highly integrated CMOS circuitry.

### Features / Benefits

- Measuring input: Angular position

Measured variable	Measuring range limits
Angular position	0...5° to 0...270°

- Capacitive scanning system / Non mechanical abrasion, low annual maintenance
- Low influence from bearing play, < 0.1%
- Accuracy  $\leq 0.5\%$  for ranges  $\leq 150^\circ$
- Torque < 0.001 Ncm
- Drive shaft fully rotatable without stops
- For building into other equipment and as an OEM product / Very compact made only 48 mm in diameter
- Marine version also available as per Lloyd's Register of Shipping
- Available in type of protection "Intrinsic safety" EEx ia IIC T6 / Can be mounted within the hazardous area (see "Table 3: Data on explosion protection")

### Layout and mode of operation

The transmitter consists of 2 main parts: the differential screen capacitor D and the electronic circuitry E (see Fig. 4).

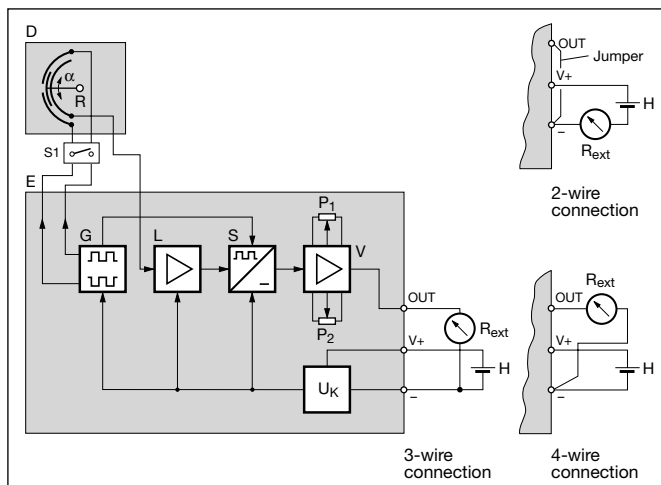


Fig. 1. KINAX 3W2 with shaft dia. 2 mm.



Fig. 2. KINAX 3W2 with shaft dia. 6 mm.



Fig. 3. Rear view with electrical connections and potentiometers for zero and FS.

Fig. 4. Block diagram.

$S_1$  = Change-over switch sense of rotation for  $\alpha > 150^\circ$

# KINAX 3W2

## Transmitter for Angular Position

The angular deflection  $\alpha$  of the device to be measured is transferred to the rotor R of the differential screen capacitor with the aid of a mechanical coupling. It is then converted into a change of capacitance proportional to the angle.

The generator G produces 2 square voltages of 8 kHz shifted in phase by 180 degrees. These voltages are applied to the differential screen capacitor.

Any change in the rotor position results in a change of current at the charge amplifier input L. This current is amplified, rectified with the synchronous rectifier S, and passes to the output amplifier V, which converts it into a load-independent DC current.

The constant voltage source  $U_k$  supplies the circuit with a stable voltage which is independent of power supply fluctuations. Zero setting and end value can be adjusted with the potentiometers  $P_1$  and  $P_2$ .

Standard ranges:	0...1 mA, 3- or 4-wire connection 0...5 mA, 3- or 4-wire connection 0...10 mA, 3- or 4-wire connection 4...20 mA, 3- or 4-wire connection 4...20 mA, 2-wire connection or 0...20 mA, 3- or 4-wire connection adjustable with potentiometer
Non-standard ranges:	0...>1.00 to 0...< 20 mA 3- or 4-wire connection

External resistance (load):

$$R_{\text{ext max.}} [\text{k}\Omega] = \frac{\text{Power supply [V]} - 12\text{V}}{\text{Output signal end value [mA]}}$$

Residual ripple in output current:	< 0.3% p.p.
Response time:	< 5 ms

### Accuracy

Reference value:	Measuring range
Basic accuracy:	Limit of error $\leq 0.5\%$ for ranges 0... $\leq 150^\circ$ Limit of error $\leq 1.5\%$ for ranges from 0...> 150° to 0...270°
Reproducibility:	< 0.2%

### Reference conditions

Ambient temperature	23 °C $\pm$ 2 K
Power supply	H = 18 V
External resistance	$R_{\text{ext}} = 0 \Omega$

### Influence effects (maxima) (included in basic error)

Linearity error	$\pm 0.4\%$ for ranges 0... $\leq 150^\circ$ $\pm 1.4\%$ for ranges from 0...> 150° to 0...270°
-----------------	--

Dependence on external resistance $\Delta R_{\text{ext max.}}$	$\pm 0.1\%$
Power supply influence	$\pm 0.1\%$

### Additional errors (maxima)

Temperature influence (-25...+70 °C)	$\pm 0.2\% / 10 \text{ K}$
Bearing play influence	$\pm 0.1\%$

### Power supply H $\rightarrow \bigcirc$

DC voltage:	Version non intrinsically safe 12...33 V Version intrinsically safe 12...30 V max. residual ripple 10% p.p. (12 V must not be understepped) Protected against wrong polarity
-------------	--

## Technical data

### General

Measured quantity:	Angle of rotation $\alpha$ $\curvearrowright$ °
Measuring principle:	Capacitive method Differential screen capacitor with contact-free, non-wearing positional pick-up. Drive shaft fully rotatable without stops

### Measuring input $\rightarrow \bigcirc$

Standard measuring ranges of rotation angle $\alpha$ :	0...10°, 0...30°, 0...60°, 0...90°, 0...180°, 0...270°
Drive shaft diameters:	2 or 6 mm resp. 1/4"
Frictional torque:	< 0.001 Ncm with shaft dia. 2 mm < 0.03 Ncm with shaft dia. 6 mm resp. 1/4"
Sense of rotation as seen from the shaft side:	$\curvearrowright \leq 150^\circ$ possible in both senses of rotation (specify the required sense of rotation). $\curvearrowright > 150^\circ$ to $\leq 270^\circ$ , sense of rotation switchable with switch S1 (initial and end value must be readjusted)

### Measuring output $\bigcirc \rightarrow$

Output variable $I_A$ :	Load-independent DC current, proportional to the input angle
Zero point correction:	Approx. $\pm 5\%$
Span adjustment:	Approx. + 5 / - 30% see Feature 6
Current limitation:	$I_A$ max. 40 mA

# KINAX 3W2

## Transmitter for Angular Position

### Installation data

Dimensions:	See section "Dimensional drawings"									
Housing:	Chromated aluminium									
Mounting position:	Any									
Electrical connections:	Soldering terminals Protection class IP 00 acc. to IEC 529									
Permissible vibrations:	5 g every 2 h in 3 directions f ≤ 200 Hz									
Shock:	3×50 g 10 shocks each in 3 directions									
Admissible static loading of shaft:	<table border="1" style="margin-left: 20px;"> <tr> <td>Drive shafts dia. Sense</td> <td>2 mm</td> <td>6 mm resp. 1/4"</td> </tr> <tr> <td>radial max.</td> <td>16 N</td> <td>83 N</td> </tr> <tr> <td>axial max.</td> <td>25 N</td> <td>130 N</td> </tr> </table>	Drive shafts dia. Sense	2 mm	6 mm resp. 1/4"	radial max.	16 N	83 N	axial max.	25 N	130 N
Drive shafts dia. Sense	2 mm	6 mm resp. 1/4"								
radial max.	16 N	83 N								
axial max.	25 N	130 N								
Weight:	Approx. 100 g									
Fixation:	3 cheesehead screws M3 or with 3 clamps									

Intrinsically safe:	Acc. to EN 50 020: 1994
Impulse voltage withstand:	1 kV, 1.2/50 µs, 0.5 Ws IEC 255-4, Cl. II
Housing protection:	IP 50 acc. to IEC 529
Test voltage:	All connections against housing 500 Veff., 50 Hz, 1 min.
Admissible common-mode voltage:	100 V, 50 Hz

### Environmental conditions

Climatic rating:	Standard version Temperature -25 to + 70 °C Annual mean relative humidity ≤ 90% or Version with improved climatic rating Temperature -40 to + 70 °C Annual mean relative humidity ≤ 95% Ex-version Temperature - 40 to + 60 °C at T6 resp. - 40 to + 75 °C at T5
Transportation and storage temperature:	- 40 to 80 °C

### Regulations

Electromagnetic compatibility:	The standards DIN EN 50 081-2 and DIN EN 50 082-2 are observed
--------------------------------	--

### Table 1: Stock versions

The following transmitter versions are available ex stock. It is only necessary to quote the Order No.:

Order Code *)	Version	Sense of rotation	Measuring range (angle)	Output signal / power supply 12 ... 33 V DC	Order No.
708 - 112D	<b>Standard</b> (non intrinsically safe) with shaft dia. Ø 2 mm, length 6 mm	Clockwise	0 ... 30°	<b>4 ... 20 mA</b> <b>2-wire connection</b> or 0...20 mA 3- or 4-wire connection (adjustable with potentiometer)	989 759
708 - 113D			0 ... 60°		993 213
708 - 114D			0 ... 90°		993 221
708 - 116D			0 ... 270°		993 239

\*) See section "Specifications and ordering information"

Instruments ex stock are factory set to output 4...20 mA for use in 2-wire connection.

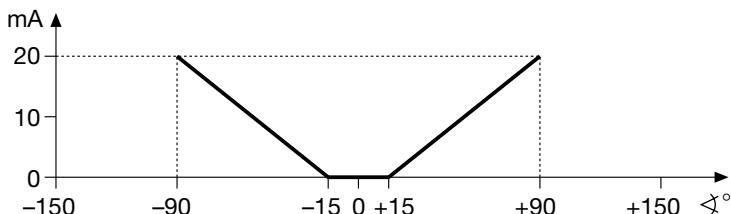
When changing from 2- to 3- or 4-wire connection the initial and end values must be readjusted with P1 and P2 respectively.

The complete Order Code 708 - .... and/or a description according to the section "Specifications and ordering information" should be stated for other versions.

# KINAX 3W2

## Transmitter for Angular Position

**Table 2: Specification and ordering information**

Features, Selection	Blocking code	no-go with blocking code	Article No. / Feature
Order Code 708 – xxxx xxxx x			708 –
<b>1. Version of the transmitter</b> (with standard shaft dia. 2 mm, at front <b>only</b> , length 6 mm*)			
1) Standard, Measuring output non intrinsically safe	A		1
2) EEx ia IIC T6 Measuring output intrinsically safe	B		2
5) Customized, (Japan) Measuring output intrinsically safe (on request)	B		5
6) Ex ia IIC T6, FTZU (Czech republic) Measuring output intrinsically safe	B		6
9) Oth versions on request	B		9
<b>2. Sense of rotation</b>			
1) Calibrated for sense of rotation clockwise	D		1
2) Calibrated for sense of rotation counterclockwise	D		2
3) For "V" characteristic	E		3
4) Both senses of rotation, calibrated and marked	M		4
Lines 1 and 2: Angle $\leq 150^\circ$ usable in both senses of rotation. Angle $> 150^\circ$ to $\leq 270^\circ$ switchable to the other direction Line 4: For measuring ranges $\leq 90^\circ$ only			
<b>3. Measuring range (measuring input) <math>\ominus \rightarrow</math></b>			
1) 0... 10 $\angle^\circ$		E	1
2) 0... 30 $\angle^\circ$		E	2
3) 0... 60 $\angle^\circ$		E	3
4) 0... 90 $\angle^\circ$		E	4
5) 0...180 $\angle^\circ$		EM	5
6) 0...270 $\angle^\circ$		EM	6
9) Non-standard $[\pm \angle^\circ]$ 0... $\geq 5$ to 0... < 270		E	9
A) "V" characteristic $[\pm \angle^\circ]$		DM	A
Line A: Specify start $M_A$ and end $M_E$ of measuring range! Observe the limits for ( $M_A [\pm \angle^\circ] \geq 10$ and $M_E [\pm \angle^\circ] \leq 150$ ) and give both angles separated by an oblique stroke, e.g. $[\pm \angle^\circ] 15/90!$			
 <p>Example of a "V" characteristic for the measuring range <math>[\pm \angle^\circ] 15 / 90</math> an an output range of 0...20 mA</p>			
Line 9: With both senses of rotation calibrated, non-standard range 0 to $\geq 5$ till 0 to < $90^\circ$			

# KINAX 3W2

## Transmitter for Angular Position

Features, Selection	Blocking code	no-go with blocking code	Article No. / Feature
<b>Order Code 708 – xxxx xxxx x</b>			<b>708 –</b>
<b>4. Output signal</b> (measuring output) $\ominus \rightarrow$ / <b>Connecting version</b> Power supply (12...33 V DC resp. 12... <b>30</b> V DC with <b>Ex</b> version)			
A) 0 ... 1 mA / 3- or 4-wire connection			A
B) 0 ... 5 mA / 3- or 4-wire connection			B
C) 0 ... 10 mA / 3- or 4-wire connection			C
D) 4...20 mA / 2-wire connection or 0...20 mA / 3- or 4-wire connection (adjustable with potentiometer)			D
E) 4 ... 20 mA / 3- or 4-wire connection			E
Z) Non-standard, 3- or 4-wire connection [mA] <span style="background-color: #cccccc; padding: 0 10px;"> </span> 0...> 1.00 to 0...< 20			Z
$R_{ext}$ max. see section "Technical data", output signal			
<b>5. Special features</b>			
0) Without	Y		0
1) With			1
Without special features (line 0): Order code complete. With special feature (line 1): The features to be omitted must be marked hereafter with / (slant line) in the order code until reaching the required feature			
<b>6. Adjustability (span adjustment)</b>			
A) Increased adjustability + 5% / – 60 %, Restriction: for angle $\geq 60^\circ$ , additional error 0.2 %		Y	A
<b>7. Drive shaft special</b>			
C) Dia. 2 mm at front, length 12 mm, dia. 2 mm rear, length 6 mm		Y	C
D) Dia. 6 mm at front, length 12 mm		Y	D
E) Dia. 6 mm at front, length 12 mm, dia. 2 mm rear, length 6 mm		Y	E
F) Dia. 1/4", length 12 mm		Y	F
G) Dia. 1/4", length 12 mm, dia. 2 mm rear, length 6 mm		Y	G
<b>8. Improved climatic rating</b>			
H) Temperature – 40 to + 70 °C, annual mean relative humidity $\leq$ <b>95%</b> instead of $\leq$ 90% for the standard version		BY	H
J) With <b>Ex</b> version Temperature – <b>40</b> to + <b>60</b> °C at T6 resp. – 40 to + 75 °C at T5, annual mean relative humidity $\leq$ <b>95%</b>		AY	J
<b>9. Marine version</b>			
L) Version GL ("Germanischer Lloyd")		Y	L

\* Lines with letter(s) under "no-go" cannot be combined with preceding lines having the same letter under "SCODE".

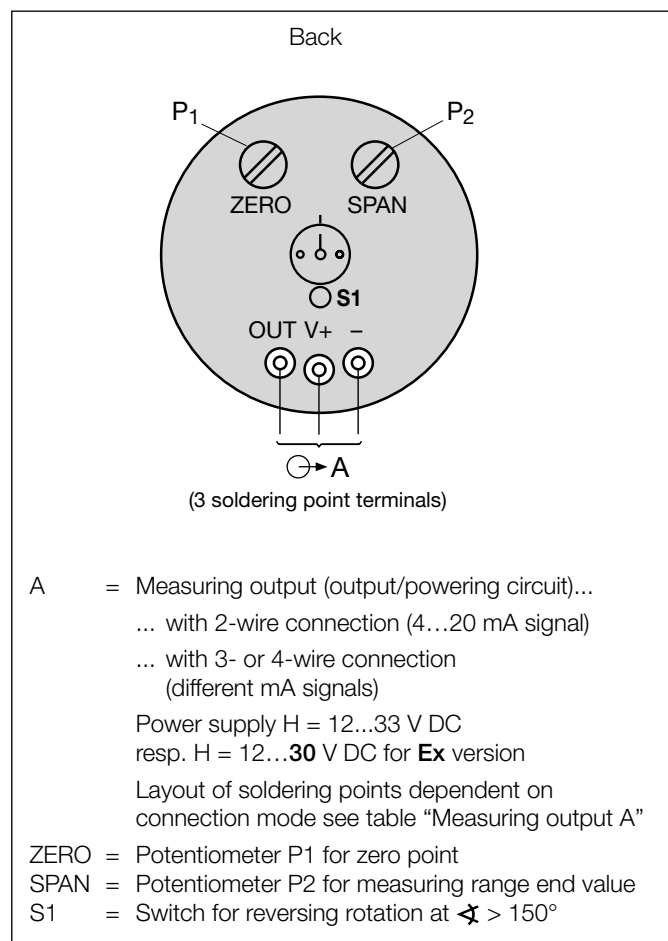
# KINAX 3W2

## Transmitter for Angular Position

**Table 3: Data on explosion protection**

Order Code	Type of protection "Intrinsically safe"		Certificates	Mounting location of device
	Instrument	Measuring output		
708 - 2 ...	EEx ia IIC T6	$U_i = 30 \text{ V}$ $I_i = 160 \text{ mA}$ $P_i = 1 \text{ W}$ $C_i \leq 10 \text{ nF}$ $L_i = 0$	Type Examination Certificate PTB 97 ATEX 2271	Within the hazardous area
708 - 5 ...	(Customized) on request		Japan	
708 - 6 ...	Ex ia IIC T6		Czech republic FTZU 98 Ex 0280	

### Electrical connections



Measuring output A	
Connection mode	Terminal allocation
2-wire connection (4...20 mA)	
3-wire connection	
4-wire connection	

$R_{ext}$  = External resistance  
 H = Power supply  
 P1, Potentiometer for zero point  
 P2, Potentiometer for measuring range end value

When changing from 2- to 3- or 4-wire connection the initial and end values must be readjusted with P1 and P2 respectively.

# KINAX 3W2 Transmitter for Angular Position

## Dimensional drawings

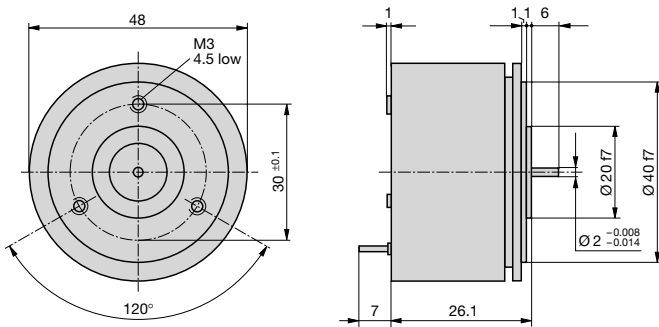


Fig. 5. KINAX 3W2 with shaft dia. 2 mm, length 6 mm, standard version.

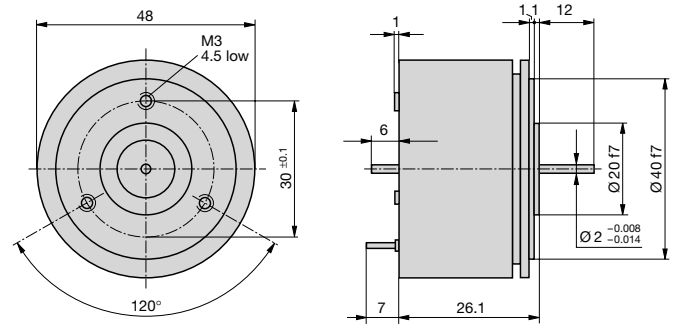


Fig. 6. KINAX 3W2 with shaft dia. 2 mm at front, length 12 mm, dia. 2 mm rear, length 6 mm.

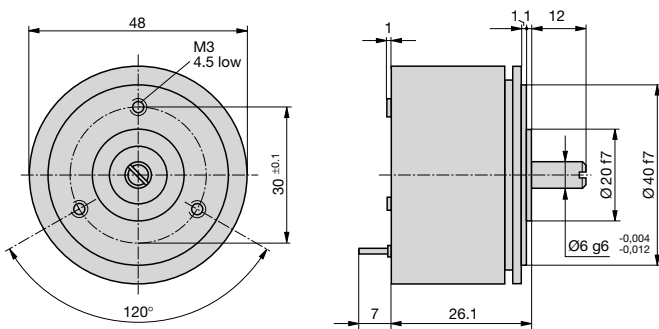


Fig. 7. KINAX 3W2 with shaft dia. 6 mm, length 12 mm.

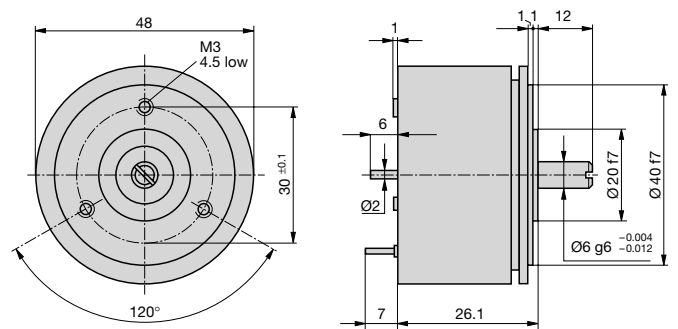


Fig. 8. KINAX 3W2 with shaft dia. 6 mm at front, length 12 mm, dia. 2 mm rear, length 6 mm.

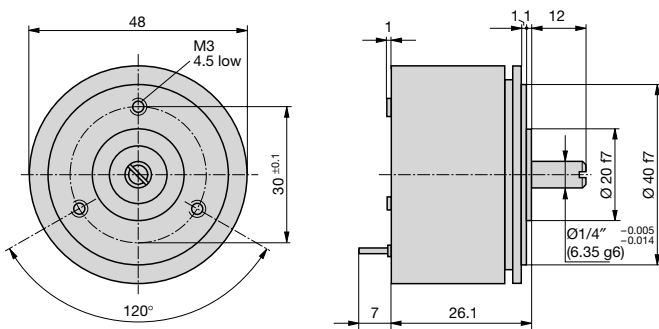


Fig. 9. KINAX 3W2 with shaft dia. 1/4", length 12 mm.

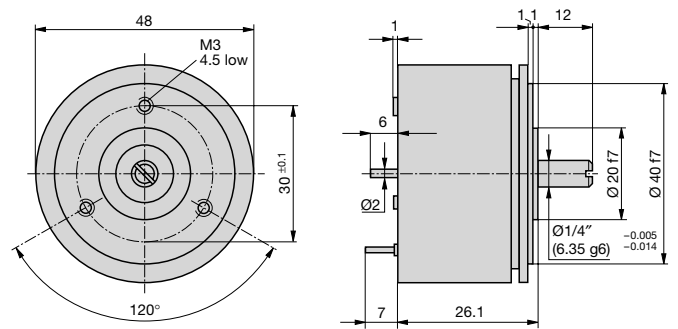


Fig. 10. KINAX 3W2 with shaft dia. 1/4", length 12 mm, dia. 2 mm rear, length 6 mm.

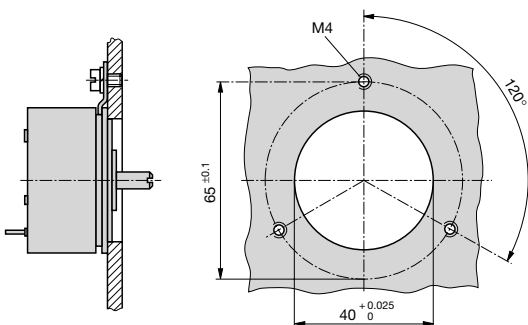


Fig. 11. Drilling plan for fixing with 3 spring clamps.

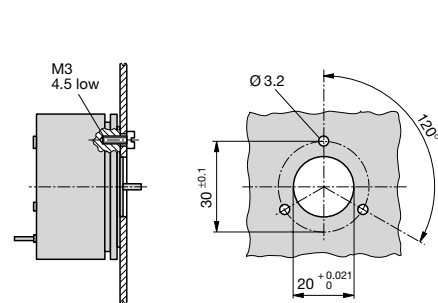


Fig. 12. Drilling plan for fixing with 3 cheesehead screws M3.

# KINAX 3W2

## Transmitter for Angular Position

---

### Standard accessories

- 3 clamps
- 1 Operating Instructions each in German, French and English
- 1 Ex approval (for instruments in Ex version only)